Joyce stainless steel screw jacks are specifically designed for positioning and lifting applications that are located in wet, corrosive or other harsh environments. In most cases, these jacks can be easily retrofitted into applications where non-stainless steel jacks have already been installed.

They are available in 2-ton through 25-ton capacities with either single lead (SWJ) or double lead (DSWJ) lifting screws. SWJ series jacks are self-locking under full lifting capacity. DSWJ series jacks offer increased travel speeds and may require a brake motor or other external locking device to hold position.

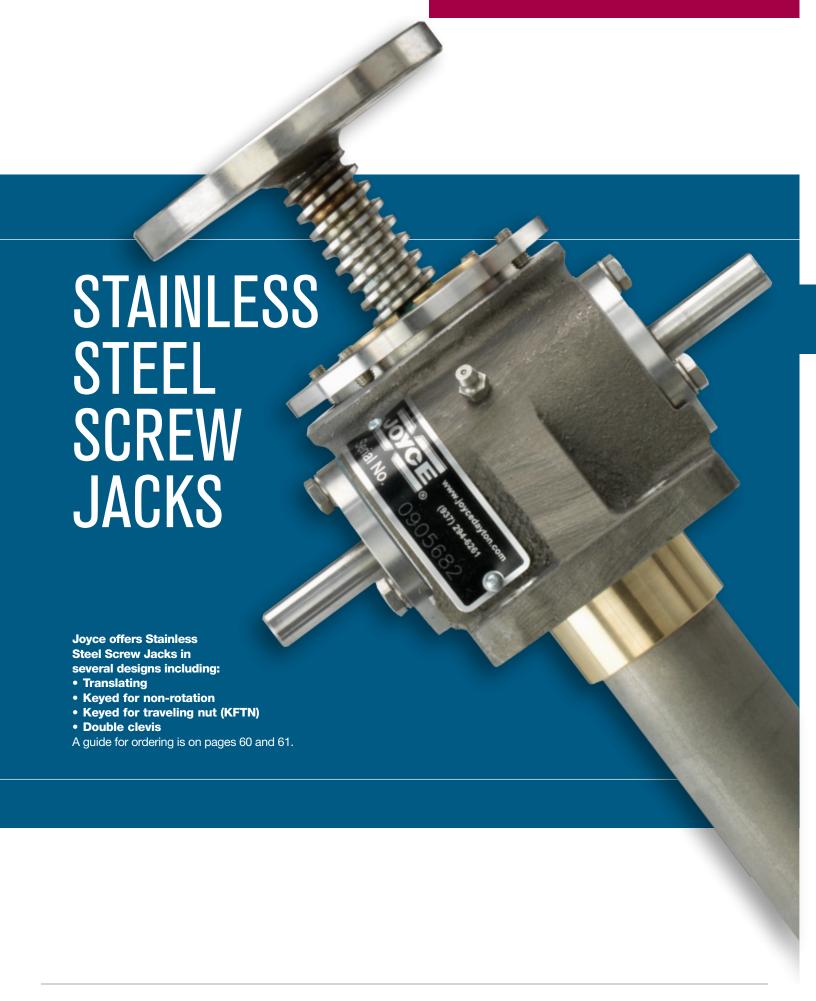
- All exposed surfaces and components feature 316 or 17-4 stainless steel construction and bronze (bushings and traveling nut).
- Nitrile rubber seals protect all internal mechanisms.
- Tapered roller or ball thrust bearings provide rugged reliability.

They are available with one of four standard screw ends or special ends to meet your requirements. Double input shafts are standard. An optional anti-backlash feature (page 181) compensates for thread wear, assuring minimum play between lifting screw and wormgear for smooth, precise operation. All jack designs can be fitted with protective boots.

Joyce can customize stainless steel jacks to meet your specifications.

Stainless steel jacks are widely used in many industries including the following:

- Food handling
- Paper mill
- Printing
- Defense
- Coastal installations



STAINLESS STEEL JACKS ORDERING INFORMATION

Instructions: Select a model number from this chart.

2-Ton	2-Ton Reverse Base	5-Ton	10-Ton	15-Ton	20-Ton	25-Ton	
SWJ62 SWJ122 SWJ242	RSWJ62 RSWJ122 RSWJ242	SWJ65 SWJ125 SWJ245	SWJ810 SWJ2410	SWJ815 SWJ2415	SWJ820 SWJ2420	SWJ1125 SWJ3225	
0SWJ62* 0SWJ122* 0SWJ242*	DRSWJ62* DRSWJ122* DRSWJ242*	DSWJ65* DSWJ125* DSWJ245*	DSWJ810* DSWJ2410*	DSWJ815* DSWJ2415*	DSWJ820* DSWJ2420*	DSWJ1125* DSWJ3225*	
l: Double Lead Screw. l: Reverse Base Jack (on For 25:1 ratio contact Jo	lf-locking, may lower under load. E ly available on 2-ton jacks). yce.) Part Num			6.00-STD	X- <u>STDX</u> -E	<u>3</u>	
Jack Configur	Inverted		Left Side Shaft Co (see below	ode Sh	ght Side naft Code se below)	Additional Options* X=Standard Jack, no additional options	
1=T1 (plain end			XXXX=Re		XX=Remove	S=Additional Specification Required (comment as necessal Anti-Backlash p. 181 A=Split Nut A90=A90 Design A95=A95 Design	
(load pad) 3=T3 (threaded er		Stainless Ste	STDX=Sta CUST=Cu For option	andard ST CU Stom ST CU	DX=Standard JST=Custom or optional shaft ides, see page 61.	Protective Boots pp. 170-173 B=Protective Boot D=Dual Protective Boo Finishes p. 182 F2=Epoxy Paint F3=Outdoor Paint Process	
4=T4 (male clevi	s)	Rise is travel e	expressed in inches	and not the actual	screw length.	Motor Options M1=Less Motor M2=Brake Motor M3=Single Phase Motor (120VAC) M4=50Hz Motor M5=Special Motor	
Jack Designs						Grease/Seals H1=High Temperature Operation H2=Food Grade	
						Screw Stops ST0=Extending ST1=Retracting ST2=Both	
	100	r Non N=Trave		puble Clevis*		* Specify as many	

^{*}Contact Joyce with your requirements.

STAINLESS STEEL JACKS SHAFT CODES

Instructions: Select the appropriate shaft codes for both right and left hand shafts. One shaft code must be specified for each side of the jack.

Screw Stops (p. 10) and Boots (p. 170-173)

Stainless steel screw stops are optional on stainless steel jacks. When specified, the closed height of the jack and the protection tube length may be increased.

When boots are added to stainless steel jacks, the closed height of the jack may be increased.

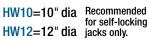
Mechanical Counters (p.180)

CNT0=0.001" Increments Note: Contact Joyce for availability and options.



Hand Wheels (p. 180)

HW04=4" dia HW06=6" dia HW08=8" dia





Geared Potentiometers (p. 175)

POTA=0-10V POTB=4-20mA

POTC=0-10V w/2 switches

POTD=4-20mA w/2 switches

IP65 rated enclosures

Encoders (pp. 176-177)

ENCA=Absolute Encoder 0-10 VDC, programmable

ENCB=Absolute Encoder 4-20mA, programmable

ENCC=Absolute Encoder CAN Open

ENCD=Absolute Encoder SSI

ENCS=Stainless Steel Incremental Encoder 1024 PPR

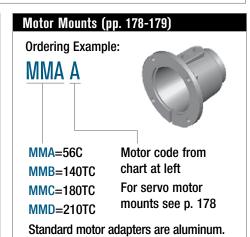
ENCX=Incremental Encoder 200 PPR

ENCY=Incremental Encoder 1024 PPR

Motors for Systems and Direct Drives (pp. 178-179)

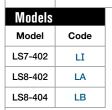
- All standard motors are 3-phase, 208-230/460 VAC or 230/460 VAC. Other motor options are available.
 Specify the appropriate motor size from the chart on the right.
- Refer to the "Additional Options" chart on the preceding page as needed.
- Brake motors (M2) are recommended for jacks that are not self locking and jacks with double lead screws.
- If the motor frequency will be varied to provide a "soft" start, an inverter duty motor may be required.

Motors	
Size	Code
1/4 HP	K
1/3 HP	Α
1/2 HP	В
3/4 HP	С
1 HP	D
1-1/2 HP	E
2 HP	F
3 HP	L
5 HP	G
7-1/2 HP	Н
10 HP	I
15 HP	J
15 HP	J





Ordering Example: LA13



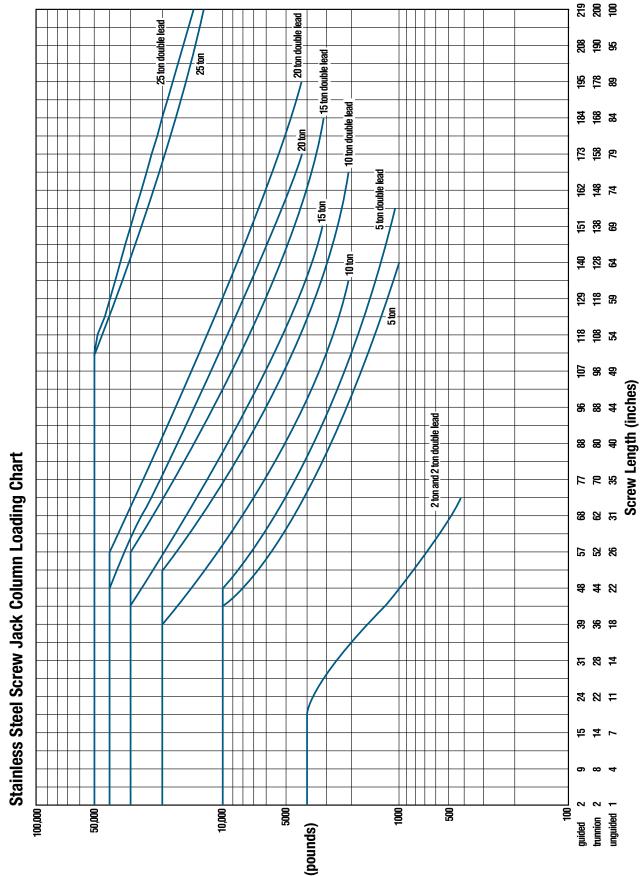
Number of DPDT Switches (see p. 174)

NOTE: Will always be 0 for LS7 models

Available	e Positions	;						
	1	2*	3	4	5	6*	7	8
Left Side Shaft Options								
Right Side Shaft Options								

- 2, 5, 10, 15, and 20 ton stainless steel jacks are available with positions #1, #3, and #5.
- 25 ton stainless steel jacks are available with positions # 1, #4, #7, and #8.
- *These positions are not standard. Contact Joyce with your requirements.

STAINLESS STEEL JACKS COLUMN LOADING



This chart includes a 2:1 Factor-of-Safety based on the Euler-Johnson equation for column loading (Oberg, Erik et al: Machinery's Handbook, 24th Edition. c. 1992 Industrial Press Inc.)
The horizontal portion of each line represents the jack's maximum dynamic capacity. Under static conditions, these lines can be exceeded. Please contact factory for assistance.

STAINLESS STEEL JACKS SPECIFICATIONS

Model	Capacity	Screw Diameter (inches)	Thread Pitch/Lead	Worm Gear Ratio	Worm Shaft Turns for 1" Travel	Tare Torque (Inch Lbs.)	Starting Torque (Inch Lbs.)	Operating Torque (Inch Lbs.)	Efficiency Rating % Approx	Screw Torque (Inch Lbs.)	Basic Jack Weight (Lbs.)	Jack Weight per Inch Travel (Lbs.)		
(R)SWJ62		2 ton 1		6:1	24	6	.041W*	.028W* @ 500 RPM	24.2			0.3		
(R)SWJ122			.250 pitch ACME 2C	12:1	48		.025W*	.015W* @ 500 RPM	22.0	.098W*	15			
(R)SWJ242	0.4			24:1	96		.018W*	.009W* @ 500 RPM	18.3					
D(R)SWJ62	Z LUII			6:1	12		.057W*	.039W* @ 500 RPM	33.7					
D(R)SWJ122			.250 pitch .500 lead ACME 2C	12:1	24		.035W*	.022W* @ 500 RPM	30.5					
D(R)SWJ242			AGIVIL 20	24:1	48		.025W*	.013W* @ 500 RPM	25.4					
SWJ65				6:1	16		.065W*	.044W* @ 300 RPM	23.0	.151W*	32			
SWJ125		1 1/2	.375 pitch STUB ACME	12:1	32	- 15	.041W*	.025W* @ 300 RPM	20.6			0.7		
SWJ245	ļ <u>.</u> .			24:1	64		.029W*	.015W* @ 300 RPM	16.7					
DSWJ65	5 ton			6:1	12		.072W*	.050W* @ 300 RPM	26.8					
DSWJ125			.250 pitch .500 lead STUB ACME	12:1	24		.045W*	.028W* @ 300 RPM	23.9					
DSWJ245				24:1	48		.033W*	.017W* @ 300 RPM	19.6					
SWJ810			.500 pitch ACME 2C	8:1	16	30	.061W*	.043W* @ 200 RPM	23.1	.195W* .228W*	- 43	1.3		
SWJ2410	1			24:1	48		.030W*	.018W* @ 200 RPM	18.8					
DSWJ810	10 ton	2	.333 pitch	8:1	12		.070W*	.062W* @ 200 RPM	31.9					
DSWJ2410			.667 lead ACME 2C	24:1	36		.035W*	.026W* @ 200 RPM	25.9					
SWJ815		2 1/4	.500 pitch ACME 2C	8:1	16	45	.069W*	.047W* @ 200 RPM	21.1	.210W*	- 59	1.4		
SWJ2415	15.4			24:1	48		.036W*	.020W* @ 200 RPM	16.6					
DSWJ815	15 ton			8:1	12		.079W*	.058W* @ 200 RPM	34.4					
DSWJ2415				.667 lead ACME 2C	24:1	36		.041W*	.025W* @ 200 RPM	27	.244W*			
SWJ820			0.1/0		.500 pitch	8:1	16		.075W*	.051W* @ 200 RPM	19.6			
SWJ2420	00 4			ACMÉ 2C	24:1	48	1	.039W*	.022W* @ 200 RPM	15.4	.227W*	77	1.0	
DSWJ820	20 ton 2 1/2	.375 pitch	8:1	10.67	60	.088W*	.061W* @ 200 RPM	24.5	.272W*	77	1.9			
DSWJ2420		.750 lead ACME 2C	24:1	32		.046W*	.026W* @ 200 RPM	19.3						
SWJ1125		on 3 3/8 .562		.666 pitch	11:1	16		.088W*	.055W* @ 200 RPM	18.3	212181*			
SWJ3225	25 ton 3 3/8		STUB ACME	32:1	48	75	.053W*	.025W* @ 200 RPM	13.5	.313W* 384W*	164	3.1		
DSWJ1125			.5625 pitch 1.125 lead ACME 2C	11:1	9.5		.106W*	.067W* @ 200 RPM	25.1					
DSWJ3225				32:1	28.5		.063W*	.030W* @ 200 RPM	18.6					

Important Note: Series DSWJ models may lower under load. Brake motors or external locking systems are recommended.

(R): Reverse Base Jack.

*W: Load in pounds.

Tare Torque: Initial torque to overcome seal and normal assembly drag. This value must be added to starting torque or operating torque values.

Starting Torque: Torque value required to start moving the rated load (dissipates to operating torque values once the load begins moving).

Operating Torque: Torque required to continuously raise a given load at the input RPM listed.

Note: If your actual input RPM is 20% higher or lower than the listed RPM, please refer to JAX® Online to determine actual torque values at your RPM.

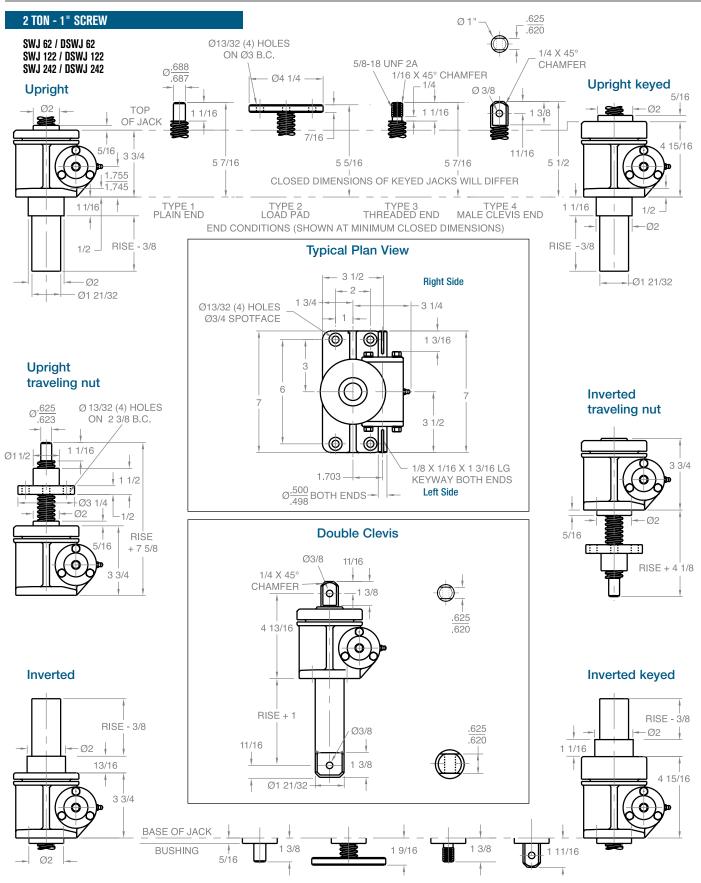
Screw Torque: Torque required to resist screw rotation (Translating Design Jacks) and traveling nut rotation (Keyed for Traveling Nut Design Jacks).

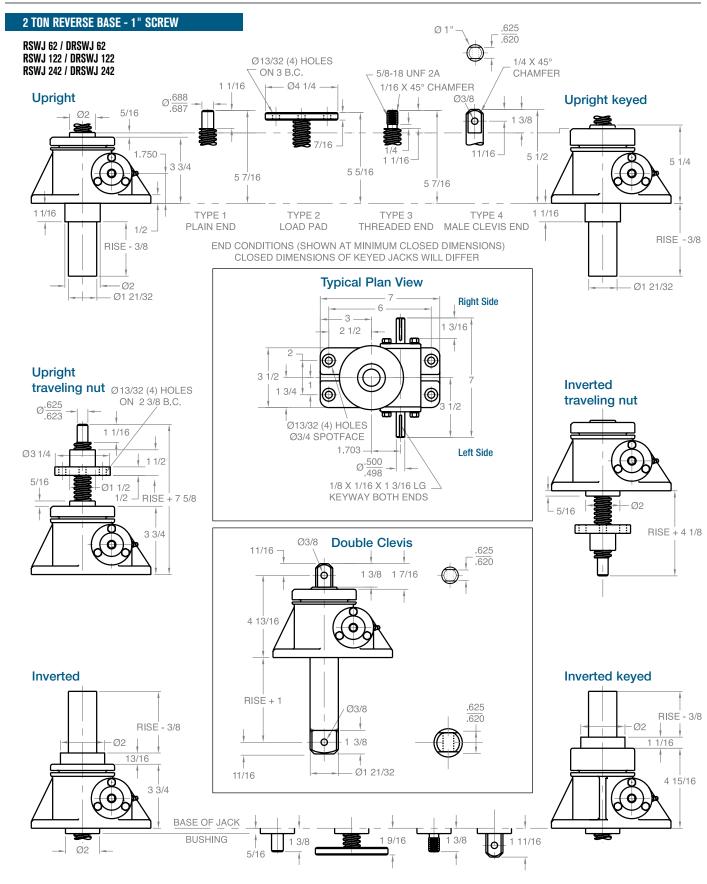
Lead: The distance traveled axially in one rotation of the lifting screw.

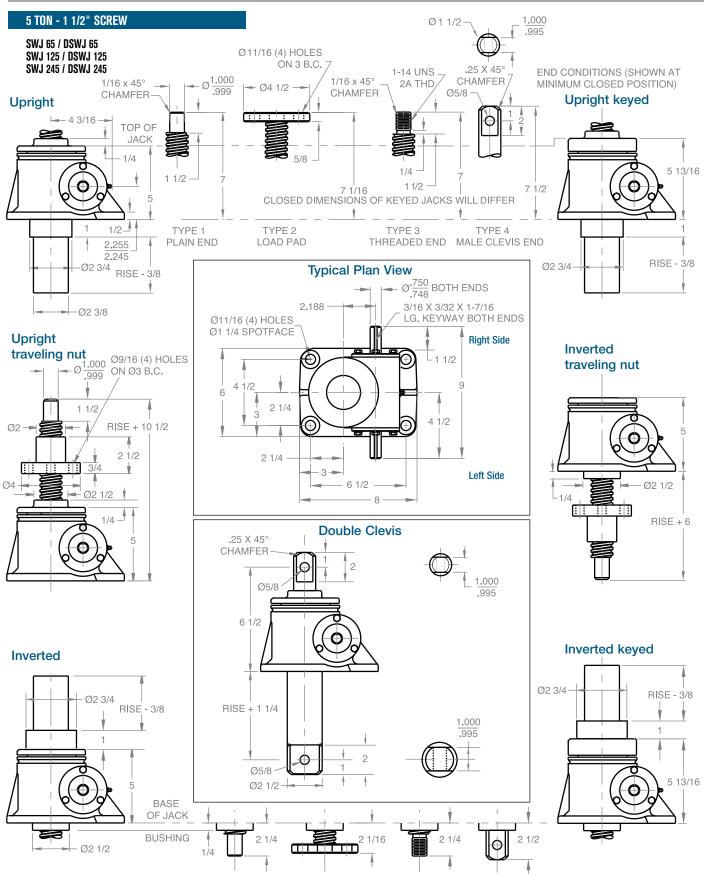
Pitch: The distance from a point on a screw thread to a corresponding point on the next thread, measured axially.

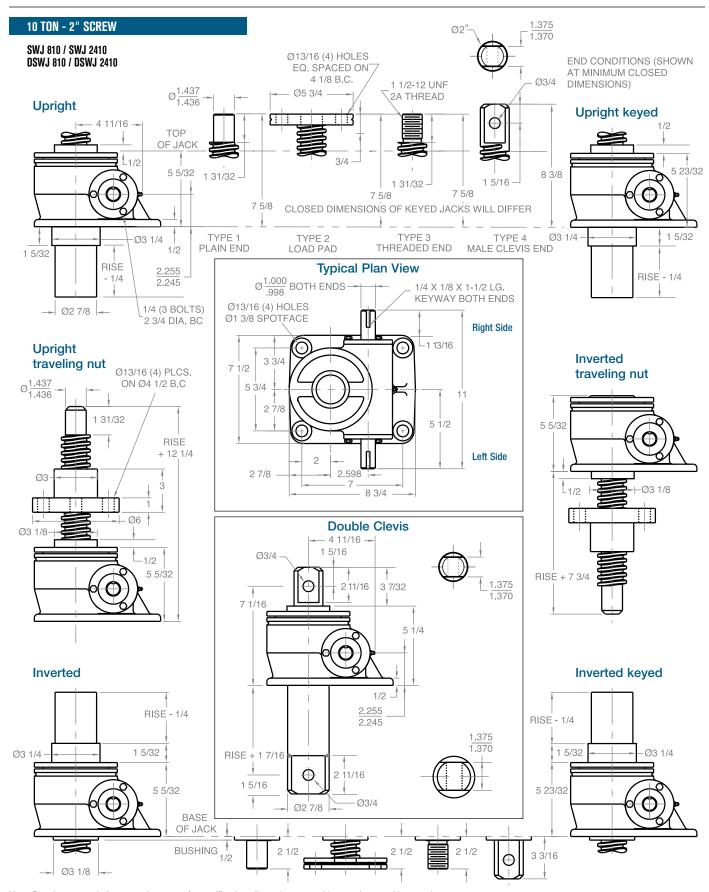
Note: This chart is provided for reference only. For specific information such as column loading, allowable continuous travel and other performance factors please refer to

JAX® Online software or contact Joyce.









 $\label{thm:conception-not} \mbox{Note: Drawings are artist's conception-not for certification; dimensions are subject to change without notice.}$

